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NPMPLE of the Disease
Onset Distribution Function
for a Survival/Sacrifice
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**Relatório Técnico
RTP-07/2001**

**Relatório Técnico
Série Pesquisa**

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Abstract

In carcinogenicity experiments with animals where the tumor is not palpable it is common to observe only the time of death of the animal, the cause of death (the tumor or another independent cause, as sacrifice) and whether the tumor was present at the time of death. These last two indicator variables are evaluated after an autopsy. Defining the non-negative variables T_1 (time of tumor onset), T_2 (time of death from the tumor) and C (time of death from an unrelated cause), we observe (Y, Δ_1, Δ_2) , where $Y = \min\{T_2, C\}$, $\Delta_1 = 1_{\{T_1 \leq C\}}$, and $\Delta_2 = 1_{\{T_2 \leq C\}}$, T_1 and T_2 have a joint distribution function F such that $P(T_1 \leq T_2) = 1$, and are independent of C . Some authors call this structure a “survival/sacrifice model”.

The interest here is to estimate the marginal distribution functions F_1 and F_2 of T_1 and T_2 , respectively (since F is not identifiable). One possible way of doing that is by using a consistent estimator \hat{F}_2 for F_2 (Kaplan-Meier, for example) and then plugging it in the loglikelihood to obtain \hat{F}_1 , the nonparametric maximum pseudo-likelihood estimator (NPMPLE) of F_1 . A characterization theorem of \hat{F}_1 is established here and an algorithm for its calculation is presented.

Key Words: survival/sacrifice; nonparametric estimation; maximum likelihood estimation.

1 Introduction

In experiments for the study of onset and mortality from undetectable irreversible diseases (occult tumors, e.g.) a possible data structure consists of the time of death, whether or not the disease of interest was present at death, and if present, whether the disease was a probable cause of death or not. This data structure is related to moderately lethal incurable diseases

when the cause of death is known. Defining the non-negative variables T_1 (time of disease onset), T_2 (time of death from the disease) and C (time of death from an unrelated cause), we observe, for the i th individual, $(Y_i, \Delta_{1,i}, \Delta_{2,i})$, where $\Delta_{1,i} = 1_{\{T_{1,i} \leq C_i\}}$, $\Delta_{2,i} = 1_{\{T_{2,i} \leq C_i\}}$, $Y_i = C_i \wedge T_{2,i} = \min\{C_i, T_{2,i}\}$, $T_{1,i}$ and $T_{2,i}$ have a joint distribution function F such that $P(T_{1,i} \leq T_{2,i}) = 1$, C_i has distribution function G and is independent of $(T_{1,i}, T_{2,i})$. Some authors call that structure a *survival sacrifice model*.

We will suppose, without loss of generality, that $Y_1 \leq Y_2 \leq \dots \leq Y_n$. In case of ties it is assumed that the observations with $(\Delta_{1,i}, \Delta_{2,i}) = (1, 1)$ occurs first, followed by the ones with $(\Delta_{1,i}, \Delta_{2,i}) = (1, 0)$ and finally by the ones with $(\Delta_{1,i}, \Delta_{2,i}) = (0, 0)$. The case 1 of interval censoring model, also called "current status" (see, e.g., Groeneboom and Wellner (1992)), can be seen as a particular case of this data structure when the disease is nonlethal, i.e., $\Delta_{2,i} = 0, i = 1, \dots, n$. The right censoring problem can also be considered as a special case of data with the structure above when a lethal disease is always present at the moment of death, i.e., $\Delta_{1,i} = 1, i = 1, \dots, n$.

For this survival/sacrifice model, the parameter space can be defined as

$$\Theta = \{(F_1, F_2) : F_1 \text{ and } F_2 \text{ are d.f.'s with } F_1 <_s F_2\},$$

where $F_1 <_s F_2$ means that $F_1(x) \geq F_2(x)$ for every $x \in \mathbb{R}$ and $F_1(x) > F_2(x)$ for some $x \in \mathbb{R}$, a consequence of $P(T_1 \leq T_2) = 1$. The loglikelihood function for this data structure is

$$\begin{aligned} \mathcal{L}(F) = & \sum_{i=1}^n \{(1 - \Delta_{1,i})(1 - \Delta_{2,i}) \log(1 - F_1(Y_i)) \\ & + \Delta_{1,i}(1 - \Delta_{2,i}) \log(F_1(Y_i) - F_2(Y_i)) \\ & + (\Delta_{1,i}\Delta_{2,i}) \log f_2(Y_i)\} + K(g, G) \end{aligned}$$

where $K(g, G)$ is a term involving only the distribution G of C .

Kodell, Shaw and Johnson (1982) also studied nonparametric estimation of $S_1 = 1 - F_1$ and $S_2 = 1 - F_2$, but their work is restricted to the case where $R(t) = S_1(t)/S_2(t)$ is non-increasing, an assumption that may not be reasonable, for example, for progressive diseases whose incidence is concentrated in the early or middle part of the life span.

Turnbull and Mitchell (1984) proposed an EM algorithm for the joint estimation of F_1 and F_2 which converges very slowly to the nonparametric maximum likelihood estimator (NPMLE) of (F_1, F_2) (provided the support of the initial estimator contains the support of the NPMLE). It should be noticed that the two-dimensional nature of their method enables us to avoid the use of Lagrange multipliers.

Van der Laan, Jewell, and Peterson (1997) proposed a weighted least squares estimator of F_1 making $F_2 = \hat{F}_{2,KM}$ (its Kaplan-Meier estimate).

Another possible way of estimating F_1 is by plugging in the Kaplan-Meier estimator $\hat{F}_{2,KM}$ of F_2 and calculating the nonparametric maximum pseudo likelihood estimator (NPMPL) of F_1 . The part of the loglikelihood involving F_1 is

$$\sum_{i=1}^n (1 - \Delta_{2,i}) \left[\Delta_{1,i} \log(x_i - \hat{F}_{2,KM}(Y_i)) + (1 - \Delta_{1,i}) \log(1 - x_i) \right] \quad (1.1)$$

where $x_i = F_1(Y_i)$. Since (1.1) can be written as

$$\sum_{i=1}^n \{\Phi(f(Y_i)) + [g(Y_i) - f(Y_i)] \phi(f(Y_i))\} w(Y_i)$$

with $f = F_1$, $\phi = d\Phi/df$, $g = 1 - (1 - \hat{F}_{2,KM})(1 - \Delta_1)$, $w = (1 - \Delta_2)/(1 - \hat{F}_{2,KM})$ and $\Phi(y) = (y - F_2) \log(y - F_2) + (1 - y) \log(1 - y)$, $0 < y < 1$, Dinse and Lagakos (1982) concluded that the values of $F_1(Y_i)$, $i = 1, \dots, n$, maximizing the pseudo loglikelihood (1.1) could be obtained applying theorem 1.10 in Barlow *et al.* (1972) (see the appendix), i.e., the NPMPLE of F_1 would be given by the isotonic regression g^* of $g(Y_i)$ with weights $w(Y_i)$, $i = 1, \dots, n$. However, that theorem is applicable to a real convex function Φ defined on \mathbb{R} while in the application above the function Φ is in fact defined on \mathbb{R}^2 since the value of F_2 is not supposed to be constant.

It should be mentioned here that, although the Kaplan-Meier estimator \hat{F}_2 is uniquely defined, except possibly at times exceeding the largest observation, the NPMPLE \hat{F}_1 is uniquely defined only over certain data-determined intervals. Specifically, \hat{F}_1 is always uniquely defined at the observed C_i 's, i.e., the observations for which $\Delta_{2,i} = 0$.

In section 2, we review the characterization of the NPMPLE of the distribution function of the time of disease onset for the case 1 of interval censoring model and present the characterization of the NPMPLE of F_1 for the survival/sacrifice model under study. In section 3, we present an example of a data set with the structure studied here and calculate the estimators \hat{F}_1 and $\hat{F}_{2,KM}$.

2 Characterization of the NPMPLE of F_1

We first present a characterization theorem for the NPMPLE of the distribution function of the time of disease onset for the case 1 of interval censoring. Defining independent positive variables X and T , we observe (T, δ) where $\delta = 1_{\{X \leq T\}}$. Here X is the (completely censored) time of disease onset and T is the time of occurrence of an examination (possibly an autopsy). The loglikelihood for F (the d.f. of X) is

$$\mathcal{L}(F) = \sum_{i=1}^n \{\delta_i \log(F(T_i)) + (1 - \delta_i) \log(1 - F(T_i))\}. \quad (2.2)$$

We will assume, without loss of generality, that $\delta_1 = 1$ and $\delta_n = 0$ since we could maximize (2.2) for the first observations with $\delta_i = 0$ by making $F(T_i) = 0$ at those points. Similarly, we could maximize (2.2) for the last observations with $\delta_i = 1$ by making $F(T_i) = 1$ at those points.

Theorem 2.1 characterizes the NPMPLE of F in terms of the Fenchel conditions (see Groeneboom and Wellner (1992) or a general form in the appendix).

Theorem 2.1 Let $\delta_1 = 1$ and $\delta_n = 0$, and $x_i = F(T_i)$, $i = 1, \dots, n$. Vector \mathbf{x}^* maximizes (2.2) if and only if

$$\sum_{j=i}^n \left\{ \frac{\delta_j}{x_j^*} - \frac{1 - \delta_j}{1 - x_j^*} \right\} \leq 0, \quad i = 1, \dots, n, \quad (2.3)$$

and

$$\sum_{i=1}^n \left\{ \frac{\delta_i}{x_i^*} - \frac{1 - \delta_i}{1 - x_i^*} \right\} x_i^* = 0. \quad (2.4)$$

Moreover, \mathbf{x}^* is uniquely determined by (2.3) and (2.4).

We will present and demonstrate an equivalent result for the survival/sacrifice model under study. Consider the problem of minimizing

$$\phi(\mathbf{x}) = - \sum_{i=1}^n (1 - \Delta_{2(i)}) \left\{ \Delta_{1(i)} \log(x_i - k_i) + (1 - \Delta_{1(i)}) \log(1 - x_i) \right\} \quad (2.5)$$

over \mathcal{K} where

$$\mathcal{K} = \{ \mathbf{x} \in \mathbb{R}^n : 0 \leq x_1 \leq \dots \leq x_n \leq 1 \}$$

subject to $x_i \geq k_i$, $i = 1, \dots, n$, where $x_i = F_1(Y_i)$, $k_i = \hat{F}_{2, KM}(Y_i)$ and the vector $\mathbf{k} = (k_1, \dots, k_n) \in \mathcal{K}$.

In other words we want to minimize $\phi(x)$ over $\mathcal{K} \cap \mathcal{L}$ where

$$\mathcal{L} = \{ \mathbf{x} \in \mathbb{R}^n : x_i \geq k_i, i = 1, \dots, n \}.$$

Since ϕ is a convex function on \mathcal{K} (a convex set of a linear vector space) and $G(\mathbf{x}) = -(\mathbf{x} - \mathbf{k})$ is a convex mapping from \mathcal{K} into a normed space, by theorem 1, page 217 in Luenberger (1969) (restated in the appendix) there exists a vector $\hat{\lambda}$ with $\hat{\lambda}_i \geq 0$, $i = 1, \dots, n$, such that

$$\inf_{\mathbf{x} \in \mathcal{K}} \left\{ \phi(\mathbf{x}) - \sum_{i=1}^n \hat{\lambda}_i (x_i - k_i) \right\} = \inf_{\mathbf{x} \in \mathcal{K} \cap \mathcal{L}} \phi(\mathbf{x}).$$

So, in order to characterize the solution of the minimization problem above we introduce a vector of Lagrange multipliers $\hat{\lambda} \in \mathbb{R}_+^n$ and define

$$\psi(\mathbf{x}, \hat{\lambda}) \equiv \phi(\mathbf{x}) - \sum_{i=1}^n \hat{\lambda}_i (x_i - k_i).$$

Note that we can take $\hat{\lambda}_i = 0$ if $\Delta_{1(i)} = 1$ since then the $\log(x_i - k_i)$ term in ϕ forces $x_i > k_i$. We may also reduce the problem to involving just those x_i 's with $\Delta_{2,i} = 0$, since those with $\Delta_{2,i} = 1$ do not contribute to the function ϕ . Thus we may take the $\hat{\lambda}_i$'s to be

$$\hat{\lambda}_i = (1 - \Delta_{2,i})(1 - \Delta_{1,i})\gamma_i$$

where we want $\gamma_i > 0$ in the cases when $\Delta_{1,i} = \Delta_{2,i} = 0$ and the solution \mathbf{x} has $x_i = k_i$.

The vector of gradients of ψ with respect to \mathbf{x} is given by

$$\begin{aligned} (\nabla_x \psi)_i &= -(1 - \Delta_{2,i}) \left\{ \frac{\Delta_{1,i}}{x_i - k_i} - \frac{1 - \Delta_{1,i}}{1 - x_i} \right\} - (1 - \Delta_{2,i}) (1 - \Delta_{1,i}) \gamma_i \\ &= (1 - \Delta_{2,i}) \left\{ \frac{1 - \Delta_{1,i}}{1 - x_i} - \frac{\Delta_{1,i}}{x_i - k_i} \right\} - (1 - \Delta_{2,i}) (1 - \Delta_{1,i}) \gamma_i \end{aligned}$$

and the vector of second partial derivatives of ψ has i th coordinate

$$\frac{\partial^2}{\partial x_i^2} \psi = (1 - \Delta_{2,i}) \left\{ \frac{\Delta_{1,i}}{(x_i - k_i)^2} + \frac{1 - \Delta_{1,i}}{(1 - x_i)^2} \right\}.$$

Thus the Fenchel conditions for minimizing ψ over \mathcal{K} are given by

$$\begin{aligned} 0 &= \langle \hat{\mathbf{x}}, \nabla_x \psi(\hat{\mathbf{x}}, \hat{\lambda}) \rangle \\ &= - \sum_{i=1}^n (1 - \Delta_{2,i}) \hat{x}_i \left\{ \frac{\Delta_{1,i}}{\hat{x}_i - k_i} - \frac{1 - \Delta_{1,i}}{1 - \hat{x}_i} \right\} - \sum_{i=1}^n \hat{x}_i \hat{\lambda}_i \\ &= \sum_{i=1}^n (1 - \Delta_{2,i}) \hat{x}_i \left\{ \frac{1 - \Delta_{1,i}}{1 - \hat{x}_i} - \frac{\Delta_{1,i}}{\hat{x}_i - k_i} \right\} - \sum_{i=1}^n \hat{x}_i \hat{\lambda}_i \end{aligned} \quad (2.6)$$

and, with $\mathbf{1}_i$ defined to be the vector with 0 in the first $i - 1$ coordinates and 1 in the coordinates i through n ,

$$\begin{aligned} 0 &\leq \langle \mathbf{1}_i, \nabla_x \psi(\hat{\mathbf{x}}, \hat{\lambda}) \rangle \\ &= \sum_{j=i}^n (1 - \Delta_{2,j}) \left\{ (1 - \Delta_{1(j)}) \left(\frac{1}{1 - \hat{x}_j} - \gamma_j \right) - \frac{\Delta_{1(j)}}{(\hat{x}_j - k_j)} \right\} \end{aligned} \quad (2.7)$$

for $i = 1, \dots, n$. We take the Lagrange multipliers to be of the form

$$\hat{\lambda}_i = (1 - \Delta_{2,i})(1 - \Delta_{1,i}) \gamma_i \mathbf{1}_{\{\hat{x}_i = k_i\}} \quad (2.8)$$

for some $\gamma_i > 0$. Then we have

$$\hat{x}_i = k_i, \quad \text{if} \quad \hat{\lambda}_i > 0 \quad \text{and} \quad \Delta_{1,i} = 0, \quad i = 1, \dots, n; \quad (2.9)$$

and

$$\hat{\lambda}_i = 0, \quad \text{otherwise.} \quad (2.10)$$

Theorem 2.2 *Suppose that (2.6) to (2.10) hold. Then $\hat{\mathbf{x}}$ minimizes ϕ over $\mathcal{K} \cap \mathcal{L}$.*

Proof: By theorem 1, page 40, in Luenberger (1969) (restated in the appendix), there exists $\hat{\mathbf{x}}$ minimizing $\phi(\mathbf{x})$ over $\mathcal{K} \cap \mathcal{L}$ since ϕ is lower-semicontinuous and $\mathcal{K} \cap \mathcal{L}$ is compact. By theorem 1, page 217 in Luenberger (1969), there exists a vector $\hat{\lambda}$ with $\hat{\lambda}_i \geq 0$ such that

$$\inf_{\mathbf{x} \in \mathcal{K}} \left\{ \phi(\mathbf{x}) - \sum_{i=1}^n \hat{\lambda}_i (x_i - k_i) \right\} = \inf_{\mathbf{x} \in \mathcal{K}} \phi(\mathbf{x})$$

subject to $x_i \geq k_i, i = 1, \dots, n$.

Moreover, from Luenberger (1969), $\hat{\mathbf{x}}$ minimizes $\psi(\mathbf{x}, \hat{\lambda})$ on $\mathcal{K} \cap \mathcal{L}$ and $\sum_{i=1}^n \hat{\lambda}_i (\hat{x}_i - k_i) = 0$. Since $\hat{\lambda}_i > 0$ if and only if $\hat{x}_i = k_i$, we have

$$\phi(\hat{\mathbf{x}}) = \psi(\hat{\mathbf{x}}, \hat{\lambda}) \leq \psi(\mathbf{x}, \hat{\lambda}) \leq \phi(\mathbf{x}).$$

But (2.6) and (2.7) are the Fenchel conditions to minimize ψ over \mathcal{K} . So, $\hat{\mathbf{x}}$ obtained from those conditions will minimize $\psi(\mathbf{x}, \hat{\lambda})$ over \mathcal{K} , and hence minimize ϕ over $\mathcal{K} \cap \mathcal{L}$. \square

3 The Iterative Convex Minorant algorithm

An algorithm can be developed based on theorem 2.2. The iterative convex minorant algorithm is an adaptation of the ICM algorithm for the calculation of the NPMLE of the distribution function of the time of disease onset for the case 2 of interval censoring (see Groeneboom and Wellner (1992)).

(0) Take $x_i^{(0)} = k_i + .02, \lambda_i = 0, i = 1, \dots, n$. Set $k = 0$.

(i) Form

$$V_i^{(k)} = \sum_{j=1}^i x_j^{(k)} \frac{\partial^2}{\partial x_j^2} \psi(\mathbf{x}^{(k)}) - \sum_{j=1}^i (\nabla_x \psi)_j(\mathbf{x}^{(k)}), \quad i = 1, \dots, n$$

$$G_i^{(k)} = \sum_{j=1}^i \frac{\partial^2}{\partial x_j^2} \psi(\mathbf{x}^{(k)}), \quad i = 1, \dots, n$$

(ii) Form the cumulative sum diagram $\left\{ (G_i^{(k)}, V_i^{(k)}), i = 1, \dots, n \right\}$, compute the greatest convex minorant $GCM^{(k)}$ and $x_i^{(k+1)}$ = left-derivative of $GCM^{(k)}$ at $G^{(k)}$.

(iii) If $x_i^{(k+1)} \leq k_i$, set $x_i^{(k+1)} = k_i$; set $\lambda_i^{(k+1)} = 0$ if $x_i^{(k+1)} > k_i$.

- (iv) Compute the Fenchel conditions (2.6) and (2.7) using the current values $\hat{\mathbf{x}}^{(k)}, \lambda^{(k)}$. If the conditions are satisfied, stop; otherwise replace $\hat{\mathbf{x}}^{(k)}$ by $\hat{\mathbf{x}}^{(k+1)}$, and continue.
- (v) Find the remaining $\lambda_i^{(k+1)}$'s from points $\{i_m\}$ where equality between $GCM^{(k)}$ and the cusum diagram holds:

$$0 = \sum_{j=1}^{i_{m+1}} (1 - \Delta_{2,j}) \left\{ (1 - \Delta_{1,j}) \left(\frac{1}{1 - \hat{x}_j^{(k+1)}} - \gamma_j^{(k+1)} \right) - \frac{\Delta_{1,j}}{(\hat{x}_j^{(k+1)} - k_j)} \right\}$$

Go to (i).

A more appropriate algorithm for the calculation of \hat{F}_1 , however, is the primal-dual interior point algorithm (see Groeneboom (1998) or Wright (1997)), which was used for the calculation of \hat{F}_1 for the example in the next section.

4 Example

An example of data with the structure considered here is given in Holland, Mitchell and Walburg (1977) and is shown in table 1. These data were studied by Dinse and Lagakos (1982) and Turnbull and Mitchell (1984) and represent the ages at death (in days) of 109 female RFM mice. The disease of interest is reticulum cell sarcoma (RCS). These mice formed the control group in a survival experiment to study the effects of prepubertal ovariectomy in mice given 300 R of X-rays.

Figure 1 shows The Kaplan-Meier estimate of F_2 and the NPMPLE of F_1 (the upper curve). We can notice that the estimate of F_2 is smoother than that of F_1 , a fact related to the different convergence rates of the estimators of those functions. As mentioned before, variable T_1 is completely censored what yields a convergence rate of $n^{-1/3}$ instead of the $n^{-1/2}$ observed for the estimation of F_2 (see Groeneboom (1996) for a calculation of a minimax

Table 1: *Ages at death (in days) in unexposed female RFM mice.*

$\Delta_1 = 1, \Delta_2 = 1$	406,461,482,508,553,555,562,564,570,574,585,588,593, 624, 626,629,647,658,666,675,679,688,690,691,692,698,699,701, 702,703,707,717,724,736,748,754,759,770,772,776,776,785, 793,800,809,811,823,829,849,853,866,883,884,888,889
$\Delta_1 = 1, \Delta_2 = 0$	356,381,545,615,708,750,789,838,841,875
$\Delta_1 = 0, \Delta_2 = 0$	192,234,243,300,303,330,339,345,351,361,368,419, 430,430,464,488,494,496,517,552,554,555,563,583, 629,638,642,656,668,669,671,694,714,730,731,732, 756,756,782,793,805,821,828,853

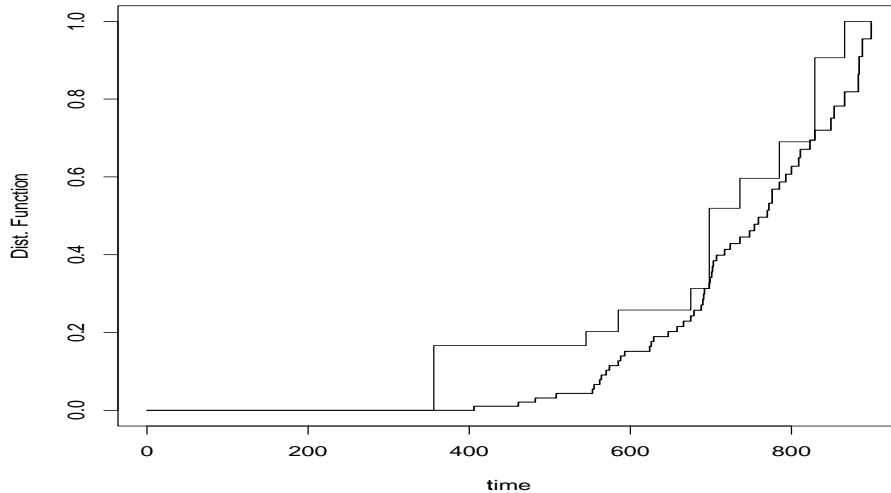


Figure 1: NPMLE of F_1 and Kaplan-Meier estimator of F_2 .

lower bound for the estimation of the time of disease onset distribution for the case 1 of interval censoring).

Discussion

Contrary to the current status data, the NPMLE of F_1 cannot be calculated using isotonic regression results. Similarly to the interval censoring case, a characterization theorem of the NPMLE of F_1 can be established in terms of the Fenchel conditions. That theorem yields an iterative algorithm for its calculation, although other algorithms can be used for that purpose.

Acknowledgements

I would like to thank Jon Wellner and Piet Groeneboom for the useful discussions and suggestions during the development of this work.

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Appendix

Definition: Let Λ be a normed linear vector space. The space of all bounded linear functionals on Λ is called the "normed dual" of Λ and is denoted Λ^* .

Definition: A cone is a subset of a linear space closed under multiplication by positive scalars.

(Lemma 2.1, page 8, Jongbloed (1995)) Let $\phi : \mathbb{R}^n \rightarrow (-\infty, \infty]$ be a continuous convex function such that ϕ is continuously differentiable on the set $\{x \in \mathbb{R}^n : \phi(x) < \infty\}$. Let $\mathcal{K} \subset \mathbb{R}^n$ be a convex cone. Then

$$\hat{x} = \arg \min_{x \in \mathcal{K}} \phi(x)$$

if and only if $\hat{x} \in \mathcal{K}$ satisfying (the Fenchel conditions)

$$\forall x \in \mathcal{K} : \langle x, \nabla \phi(\hat{x}) \rangle \geq 0,$$

$$\langle \hat{x}, \nabla \phi(\hat{x}) \rangle = 0.$$

(Theorem 1, page 40, Luenberger (1969)) (Weierstrass) An upper semicontinuous functional on a compact subset \mathcal{M} of a normed linear space \mathcal{X} achieves a maximum on \mathcal{M} .

(Theorem 1, page 217, Luenberger (1969)) Let \mathcal{X} be a linear vector space, Λ a normed space, \mathcal{K} a convex subset of \mathcal{X} , and C the positive cone in Λ . Assume that C contains an interior point.

Let ϕ be a real-valued convex functional on \mathcal{K} and G a convex mapping from \mathcal{K} into Λ . Assume the existence of a point $x_1 \in \mathcal{K}$ for which $G(x_1) \leq \mathbf{0}$ (i.e., $G(x_1)$ is an interior point of $N = -C$).

Let

$$\mu_0 = \inf f(x) \tag{4.11}$$

subject to $x \in \mathcal{K}$, $G(x) \leq \mathbf{0}$, and assume μ_0 is finite. Then there is an element $\lambda_0^* \geq \mathbf{0}$ in Λ^* such that

$$\mu_0 = \inf_{x \in \mathcal{K}} \{f(x) + \langle G(x), \lambda_0^* \rangle\}. \tag{4.12}$$

Furthermore, if the infimum is achieved in (4.11) by an $x_0 \in \mathcal{K}$, $G(x_0) \leq \mathbf{0}$, it is achieved by x_0 in (4.12) and

$$\langle G(x_0), \lambda_0^* \rangle = 0. \tag{4.13}$$